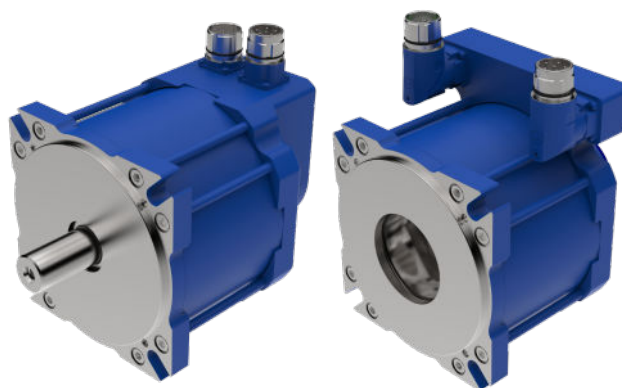




Swedish Innovative Servo Motion
Engineering Since 1994



HDD/ICM 14N - Data sheet

Electric data

Value	Unit	Winding	
		Pa (400VAC)	Ma (230VAC)
Number of poles		20	20
Number of pole pairs		10	10
Inductance/Phase	mH	2.25	0.89
Resistance/Phase	Ohm	0.32	0.14
Resistance/Phase-Phase	Ohm	0.64	0.29
Back EMF/Phase-Phase RMS	Vs/rad	0.90	0.55
Back EMF @ 1000 rpm	V	95	58
Torque constant (RMS)	Nm/A	1.57	0.96
Max rail voltage	V	750	750
Recommended peak current	A	30	49
Torque at recommended peak current	Nm	45	45

For higher torques, see next page.

Mechanical data (resolver feedback)

Value	Unit	HDD14N	
		no brake	brake
J	kgcm ²	32.6	33.0
Mass	kg	10.0	10.5

Holding brake

Value	Unit	
Torque	Nm	9
J	kgcm ²	0.4
Voltage	V DC	24
Power	W	12

Thermistors

Overheat protection consists of triple PTC thermistors.
One on each phase.

R @ 25 C	100 to 350 Ohm
R @ 145 C	< 1650 Ohm
R @ 155 C	> 4 kOhm

Protection class

HDD motors comply with the requirements for IP 65. IP-67 is available on request.

Insulation class

The insulation system complies with the requirements of EEC LV Directive 73/23/EEC and 93/68/EEC. Test report E9911111E01.

Motor name structure

Type	Flange size	Stator length	Winding	Feedback	Power connector	Brake	Shaft key	Options
HDD	14	N	-Pa	-A	-A	-A	-A	-AAA

Type

HDD = shaft motor, ICM = internal coupling motor.

Flange size

Approximate in cm. 14 = 140 mm.

Stator length

HDD: J(shortest), N, Q, R (longest), ICM: J (shortest), N (longest).

Winding

Suitable rail voltage at 3000 rpm.

Pa	560V
Ma	320V

Feedback

See the feedback list on www.hddservo.com/product-options/

Power connector

Many different pinouts available; see www.hddservo.com/product-options/

Brake

A = no brake, D = holding brake. Data see above.

Shaft key

A = shaft with key, B = shaft without key.

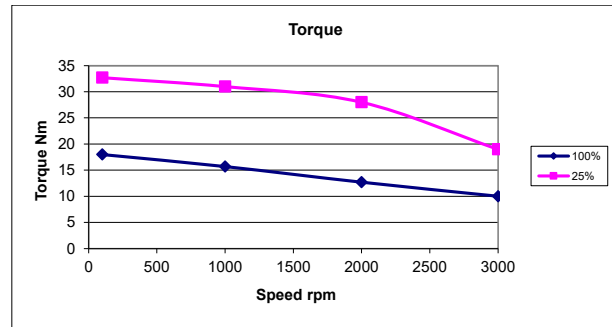
Options

AAA = standard. For other options please contact HDD.

Torque

Torque in Nm at 90°C temp rise (median temp rise, i.e. average between min and max temp for 25% cycle).

Duty cycle	100%	25%
100rpm	18.0	32.7
1000rpm	15.7	31.0
2000rpm	12.7	28.0
3000rpm	10.0	19.0



Current

Current at 90°C temp rise, in Ampere rms.

Winding	Pa	Ma	Pa	Ma
	100%		25%	
100rpm	12.5	20.5	23.2	38.0
1000rpm	11.2	18.3	22.3	36.5
2000rpm	9.2	15.1	21.0	34.4
3000rpm	7.7	12.6	19.0	31.1

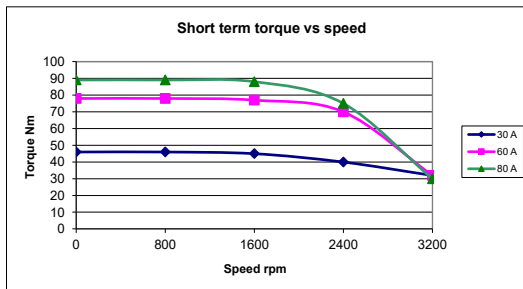
Data were measured on an HDD14N-Pa series motor mounted on a vertical 450 x 375 x 30 mm steel plate in free air, with a winding temperature rise of 90°C and driven by a commercially available inverter.

Important note on peak torque and currents

The HDD/ICM motors are capable of high peak torques. At very high peak torques the permitted pulse time is very limited as a high current in a very small motor causes rapid temperature rise in the copper winding. The protection thermistor will not react fast enough to protect the winding during high pulse loads. A 80A rms current to a HDD14N-Pa will give some 90 Nm, but the copper winding temperature will increase with some 40°C per second. This is not a problem for short pulses of < 0.5 seconds as long as the rms value of the current is kept below some 10 A. The short term torque graph below represents acceleration ramps at various commanded currents; the actual currents may be lower if the driver has not been able to compensate for the high acceleration.

Torque at various commanded currents

HDD 14N-Pa at 560V rail voltage



Maximum load on shaft at life expectancy 20,000 h (shaft motors only)

Maximal axial load (push): 1000 N at 500 rpm, 300 at 3000 rpm.

Maximal axial load (pull): 100 N at all speeds.

Maximal radial load is given by the curves below.

